

Training Day 1

Date: Tuesday, 3. (German) or 10. (English) September 2024

Aim of the day: Successfully perform the commissioning of a standard axis

Instructors: Yannik Zemp, Filippo Marinho

Participants (8): ...

Material:

- Motors, drives, and power supplies from Triamec

Preparation:

- The participants bring their own laptops
 - [Current TAM Software](#) installed
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MORNING

Start: 08:30

Aim: Get to know the hardware and software, commissioning and control theory

Product overview (HW) ~30min

- Types of drives, Option Modules
- Interfaces of the Drive
 - Encoder
 - Motor
 - STO (Safety-Functions)
 - DigIO
 - USB
 - Ethernet (Bridge-Mode)
 - Trialink/EtherCAT
 - Logic Supply
 - Option Modules
- Power Supply
 - Funktion TP (TPDC)
 - Supply via transformer or switch-mode power supply
- Field Busses
 - EtherCAT
 - EtherCAT Master
 - Trialink
 - TL Triamec PCI-Express Adapter Card
- Shielding / Grounding

TAM System Explorer ~1h

- Documentation
- Establish connection (Preferences?)
- Triamec Workspace
- How to use TAM System Explorer
 - Stations (Device Information)
 - Register Tree (Topology)
 - (Information)
 - Parameters: Prepare/Commit/Revert Parameters
 - Commands
 - Signals: Scope
 - Axis Monitor
 - Emergency Stop & Stop (Halt), Global Keys
 - Override
 - VM State
 - Errors / Warnings
 - Scope 1 - basic introduction
 - Pan/Zoom
 - Sampling Time
 - Zoom/Pan
 - Repeat/Single Mode
 - Run Stop
 - Analysis
 - Save/Load Data
 - Templates
 - Tab Panel
- Tam Configuration
 - Save/Load Configuration
 - Persistence on the Drive
 - Open in Editor / Compare with Diff-Tool
 - Simulated Mode
- Modules
 - Add / Remove
 - Plug-in concept
 - Structure and content of Axis Group Module
 - Frequency response tool
- Firmware Update (Official Source Website)
- Debug opportunities
 - Report
 - Browser
 - Logs: Severity Settings, TSE Log
 - Dump files

COFFEE BREAK

10min

Theory ~30min

- Control structure
- Commutation variants and Iq/I_d system

Basics of Commissioning ~1h

- How to configure the parameters?
 - Go through relevant parameters and explain with a concrete example (AKM22E).
 - Motor
 - Thermal Protection
 - Temperature Sensors
 - I²T
 - Path Planner
 - Relevance of parameters
 - Position Controller
 - Feed Forward
 - Output Limit
 - Encoder
 - Topology (Option Module)
 - Supported Encoder types
 - Remark about the power supply of Magnescale encoders
 - Controller -> Bode
 - Why two control systems?
 - Commutation
 - Phasing
 - Differences between encoder types
 - Current Controller
 - Homing
 - Routines
 - Differences between encoder types
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LUNCH 12:15

AFTERNOON

Start: 13:30

Aim: Hands-on experience with commissioning and tuning of an axis

Commissioning and Tuning with practical exercise ~2h

- Overview Commissioning
- Frequency Response Measurement

- Exercise
 - Tuning with Bode and Nyquist Plots
 - Exercise
 - Feed Forward
 - Tests in Time and Frequency domain
 - Exercise
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COFFEE BREAK

10min

Measurements, Scope 2 ~1h

- Trigger
- Axes
- Auto Save
- Streaming
- Data Analysis, FFT, STD

Conclusion of the day ~15min

- Summary
 - Outlook
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End: ~ 17:00